

JONGSEONG BRAD CHOI, Ph.D.

Assistant Professor

Department of Mechanical Engineering

The State University of New York, SUNY Korea

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RESEARCH INTERESTS

Visual Analytics; Structural Health Monitoring and Prognostics; Computer Vision; SLAM; Deep Learning; Photogrammetry; Aerial Manipulation; Hypersonic Propulsion; Compressible Flow

EDUCATION

PhD., Mechanical Engineering, Purdue University, West Lafayette, IN, USA	05/2020
Lissertation: Automating Visual Data Collection and Analytics toward Lifecycle Management of E	Engineering Systems
MSc., Mechanical Engineering, University of Mississippi, University, MS, USA	05/2014
+ Thesis: Parametric Scramjet Analysis	
BSc., Mechanical Engineering, University of Mississippi, University, MS, USA	05/2012
EMPLOYMENT HISTORY	
Assistant Professor, Department of Mechanical Engineering	08/2020 – Present
The State University of New York, SUNY Korea, Incheon, South Korea	
Research Assistant Professor, Department of Mechanical Engineering	08/2020 – Present
The State University of New York, Stony Brook University, Stony Brook, USA	
Postdoctoral Researcher, Systems Assessment Center	. 06/2020 – 07/2020
Argonne Nation Laboratory, Lemont, IL, USA	
Graduate Research Assistant, School of Mechanical Engineering	08/2014 – 05/2020
Purdue University, West Lafayette, IN, USA	
Graduate Research and Teaching Assistant, Department of Mechanical Engineering	08/2012 – 05/2014
Unversity of Mississippi, University, MS, USA	
PROFESSIONAL POSITION	
Chair Committee, Board of Business	<u>-</u>
The Korean Society of Mechanical Engineers (KSME) – Division of Reliability Engineering, South Korean	a
Chair Committee, Board of Internal Business	01/2021 – Present
The Korean Society of Prognostics and Health Management (KSPHM), South Korea	
Committee, Board of Industry-Academia Collaboration	01/2025 – Present
The Korean Society of Mechanical Engineers (KSME) – Division of IT-Intelligence Convergence, South	
Committee, Board of Academic Affairs	01/2025 – Present

The Korean Reliability Society, South Korea

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30.	(PI) MetaReal: Commercialization of Hyper-Realistic Real Estate Spatial Information Metaverse Technology supported by RAPA (Korea Radio Promotion Association), awarded funding amount of 683 million KRW (equivalent to 568.523K USD)	05/2025 – 12/2027 (ongoing)
29.	(PI) PINN based EV Energy Consumption PHM model and EV Navigation System Development supported by Hyundai Motor Group, awarded funding amount of 60 million KRW (equivalent to 50K USD)	04/2025 – 11/2025 (ongoing)
28.	(PI) True Twin: Al-based Hyper-Realistic Industrial Digital Twin for Distributed Collaborative and Predictive Facility Maintenance in Mixed Reality supported by NRF (National Science Foundation of Korea) under Grant No. NRF-2025R1F1A106361711, awarded funding amount of 1207.849 million KRW (equivalent to 1,007k USD).	03/2025 – 02/2030 (ongoing)
27.	(PI) Ultracapacitor Smart Cell Balancing 2.0 Algorithm Development supported by LS Materials and KETI (Korea Electronics Technology Institute) awarded funding amount of 25 million KRW (equivalent to 20.8k USD).	02/2025 – 09/2025 (ongoing)
26.	(PI) AI-based Ultra-High-Resolution 3D Modeling Academic Service for Scaled-Down Models of Reactor Internal Structures, supported by Korean Institute of Machinery and Materials (KIMM), award funding of 20 million KRW (equivalent to 16.7k USD)	01/2025 – 06/2025
25.	(PI-internal) Graduate Student Research Assistantship Program , support by SUNY Korea R&BDF, awarded funding of 17.6 million KRW (equivalent to 14.7k USD)	09/2024 – 12/2024
24.	(PI-internal) International Joint Research Support Fund , support by SUNY Korea R&BDF, awarded funding of 9 million KRW (equivalent to 7.5k USD)	06/2024 – 11/2024
23.	(PI) Development of a 3D-based Ship Assessment Platform and Utilization through Web Service, supported by KR (Korean Register of Shipping), awarded funding of 44 million KRW (equivalent to 36.7k USD)	03/2024 – 10/2024
22.	(PI) Development of Image-based Indoor 3D Modeling Technique for Facility Digital Twin Models, supported by MDS Intelligence Inc., awarded funding of 60.5 million KRW (equivalent to 50.4k USD)	11/2023 – 2/2024
21.	(PI) 2023 Global Product Service Localization Research, supported by ITP (Incheon Technopark), awarded funding of 5 million KRW (equivalent to 4.2k USD).	08/2023 – 10/2023
20.	(PI) Remote Inspection for Shipment Engine Reliability exploiting Metaverse and Digital Twin Models, supported by KR (Korean Register of Shipping), awarded funding of 44 million KRW (equivalent to 36.7k USD)	05/2023 – 12/2023
19.	(PI) 2023 Steam Activity Research Program for Incheon Academy of Science & Arts (IASA), supported by IASA, awarded funding of 16 million KRW (equivalent to 13.3k USD).	03/2023 – 12/2023
18.	(PI) 2022 Global Product Service Localization Research , supported by ITP (Incheon Technopark), awarded funding of 5 million KRW (equivalent to 4.2k USD).	09/2022 – 12/2022
17.	(PI) Emulation and Enhancement of Human Capability on Infrastructure Assessment: Engineering Soft-Power Engaged Monitoring and 3 Major Techniques supported by NRF (National Science Foundation of Korea) under Grant No. NRF-2022R1F1A106361711, awarded funding amount of 101.43 million KRW (equivalent to 84.5k USD).	06/2022 – 02/2024

- 16. (PI) Development of An Integrated MCU (Mechanical Control Units) Component and 05/2022 - 12/2022 Module Corresponding to Smart-Car Complex Control System supported by ITP (Incheon Technopark), awarded funding of 28 million KRW (equivalent to 23.3k USD). 15. (PI) Space Exploration and In-Situ Resource Utilization Center (SRC) supported by NRF 04/2022 - 12/2026 (National Research Foundation of Korea) under Grant No. NRF-2022M1A3C2085237, (ongoing) awarded funding of 475 million KRW (equivalent to 395.8k USD). 14. (PI) Development of IMU-based self-stabilizing autonomous guided vehicle (AGV) control 03/2022 - 07/2022 system and hardware supported by AIDL co., awarded funding of 5.7 million KRW (equivalent to 4.8k USD). 13. (PI) 2021 Global Product Service Localization Research, supported by ITP (Incheon 10/2021-12/2021 Technopark), awarded funding of 10 million KRW (equivalent to 8.3k USD). 12. (PI, Equipment Grant) Two Electric Rover Vehicles, Velodyne LiDar Puck, and RTKGPS 06/2021 - 06/2031 Sensor, supported by KICT (Korea Institute of Civil Engineering and Building Technology), (ongoing) awarded funding equivalent to 53 million KRW (equivalent to 44.2k USD). 11. (Co- PI) XR based Intuitive Inventory System for Smart Factory, supported by RAPA (Korea 04/2021 - 12/2021 Radio Promotion Association), awarded funding of 200 million KRW (equivalent to 167k USD), 3 conference paper published [C6],[C7],[C8]. 10. (PI) Automating Visual Assessment of Infrastructure exploiting Computer Vision and Big 03/2021 - 02/2022 Visual Data, supported by NRF (National Science Foundation of Korea) under Grant No. NRF-2021R1G1A1012298, awarded funding of 30 million KRW (equivalent to 25k USD), 1 journal paper published [J10], [A1]. Integrating Human and Machine for Post-Disaster Visual Data Analytics, supported by NSF 9. 01/2019 - 05/2020 under Grant No. NSF-1835473, 2 journal paper published [J7], [J9]; 1 journal paper accepted [J10]; 1 conference paper accepted [C9]; 1 proposal submitted [P5]. 8. STORM: Safeguarding Cultural Heritage through Organizational Resources Management, 04/2017 - 05/2020 collaborated with EU (European Union) under Grant No. H2020 n. 700191, 1 conference paper published [C4]; 1 journal paper under review [J13]. 7. RETH: Resilience ExtraTerrestrial Habitat, supported by New Horizon Program at Purdue 08/2018 - 01/2019 University and NASA (The National Aeronautics and Space Administration), 3D models & videos were published in numerous articles worldwide (e.g., usatoday.com, space.com,
- 6. Active Citizen Engagement to Enable Lifecycle Management of Infrastructure Systems, 05/2017 08/2018 supported by NSF under Grant No. NSF-1645047, 2 journal paper published [J6], [J8].

etc.); Available in https://phys.org/news/2019-07-humans-lava-tubes-moon.html, 1

- 5. Vision-based Visual Inspection System for A Large Number of Aerial Images, 1 journal 01/2017 12/2017 paper published [J6]; 1 proposal funded [P5]
- 4. Sensor Integrated Autonomous Flight UAV System Development, 2 proposals generated 05/2016 05/2021 [P1], [P2]
- 3. Automated Region-of-Interest Localization and Classification for Facility Visual 05/2015 05/2017 Assessment, 1 journal paper published [J5]; 1 conference paper published [C2].

conference paper published [C5].

- 2. Image-Based Collection and Measurements for Construction Pay Items, supported by 05/2015 08/2017 INDOT (Indiana Department of Transportation) under Grant No. SPR-4006, 1 journal paper published [J4]; 1 conference paper published [C1]; 1 technical Report published [C3].
- Parametric Analysis of Scramjet Engine Varying Material and Fuel (Research Assistant), 08/2012 05/2014 supported graduate program by University of Mississippi, 3 journal papers published [J1], [J2], [J3]; 1 Master thesis generated

TEACHING RECORDS

Course Teaching		
MEC 559: (Graduate Course) Mobile Robotics and Autonomous Vehicle – Computer Vision and Sp 24, 25		
Control at the State University of New York, SUNY Korea		
MEC 510: (Graduate Course) Object-Oriented Programming for Scientists and Engineers – Visual	Sp22, 23, 24, 25	
Analytics for Mechanical Engineers at the State University of New York, SUNY Korea		
MEC 410: Design of Machine Elements at the State University of New York, SUNY Korea	Sp22, 23	
MEC 301: Thermodynamics at <i>the State University of New York, SUNY Korea</i> : Recorded the highest	Fa20, 21, 22, 23, 24	
course evaluation score in the department		
MEC 320: Numerical Methods in Engineering Design and Analysis at the State University of New	Fa21, 22, 23, 24	
York, SUNY Korea		
MEC 363: Mechanics of Materials at the State University of New York, SUNY Korea	Sp21	
Student Advising (6 Ph.D., 2 Master's, 13 Bachelor's students in Aug 2025)		
RAs - Ph.D. Course, the State University of New York, SUNY Korea		
Jonathan Boyack: Engineering-Soft-Power engaged Remote Sensing and Smart City	2022.01 – Present	
Ricardo Ortiz: Development of RKTGPS-based Autonomous Vehicle using ROS	2024.01 – Present	
Hansol Lim: LiDAR-3DGS System Development for SLAM	2024.07 – Present	
Alfredo Valenzuela: PTZ Camera Calibration and App Development	2025.01 – Present	
Jee Won Lee: MicroSplats: Image-based 3D Reconstruction using Micro Gaussian Splatting	2025.07 – Present	
Hanbeom Chang: Development of LiDAR-RGB Sensing System	2025.08 – Present	
RAs - Master's Course, the State University of New York, SUNY Korea		
Sooyeun Yang: Digital Twin Operation through Omniverse	2025.03 – Present	
Hyeoji Chang: 3D Gaussian Splatting SLAM	2025.01 – Present	
 Hanbeom Chang: Development of LiDAR-RGB Sensing System (Graduated) 	2023.02 – 2025.06	
 Jee Won Lee: Camera Optimization for Gaussan Splatting (Graduated) 	2022.03 – 2025.06	
 Alfredo Valenzuela: Long-Distance Monitoring using PTZ Camera Sensing (Graduated) 	2022.08 – 2024.12	
 Hansol Lim: NeRF-based 3D Video Generation (Graduated) 	2022.08 – 2024.06	
 Ricardo Ortiz: RTKGPS-based autonomous driving (Graduated) 	2021.08 – 2023.12	
 Jonathan Boyack: Non-Thesis option (Graduated) 	2020.08 – 2021.12	
RAs - Undergraduate Course Present		
Cheyul Im: Hyper-Resolution 3D Reconstruction and Blender	2025.01 – Present	
 Sungwook Choi: Multimodal Remote Sensing through Mixed/Virtual Reality 	2025.01 – Present	
Gunwoo Kim: Camera Calibration for Rapid Projection Matrix Generation	2025.01 – Present	
Dissertation Committee, Ph.D. Student, the State University of New York, SUNY Korea		
• Mark Anthony Rotor: Designing tidal turbine (HATT) blades utilizing Artificial Neural	2021.01-2023.08	
Network (ANN) where I serve as chair of the committee		

• **Saebom Jin**: Breaking the Vicious Cycle: How Vulnerable Cities Can Develop Smart and 2023.04–2023.12 Sustainable with Adaptation Planning

Theis Committee, Master Student, the State University of New York, SUNY Korea

2021.08-2023.06

• **Suyeon Lee**: Prognostics using Nonlinear Cumulative Damage Model for Electronic Devices where I serve as member of the committee

Undergraduate Supervisee Graduations, the State University of New York, SUNY Korea

- Hye Jee Chang: Visual Analytics (Fa20, Sp21), Georgia Tech, Undergrad's program, USA
- Pureun Jeong: Visual Analytics (Fa21, Sp22), Yujin Robotic Co. South Korea
- Sooyon Chang: SLAM for visual assessment (Fa20, Sp21, Fa21), Purdue Univ., Ph.D. program, USA
- Hyunseung Cha: Motor driver development for EV (Fa20, Sp21, Fa21), Hyundai Rotem, South Korea
- Prince-David Malendele: SLAM for visual assessment (Fa20, Sp21), Brookhaven Natl. Lab., USA
- Jimin Shin: Lidar sensing and rover control (Sp22, Fa22), SUNY Korea, Master's program, South Korea
- Seunghyun Cha: Lidar sensing and rover control (Sp22, Fa22), KT Co., South Korea
- Dannielle Macmaster: Aerospace metabus platform development (Sp23, Fa23), undecided
- Leeloy Makusha: Aerospace metabus platform development (Sp23, Fa23), UT Alington Master's Program
- Jaewon Lee: PTZ Camera Control (Fa22, Sp23), SUNY Korea, Master's program, South Korea
- Yoonseong Kim: Indoor Mapping through Photogrammetry (Fa23, Sp24), KITECH, South Korea
- Sambridha Bhattarai: Hexabot Control and Manipulation (Fa23, Sp24), Found a start-up
- Soo-Jung Chi: LiDAR-RGB 3D Modeling of a Large Facilities (Sp24, Fa24), Janssen Korea, South Korea
- Hojin Song: Vision-based Autonomous Vehicle, Korean Military Service, South Korea
- Eunjae Lee: 3D Reconstruction and Vision Sensing, Skyes Blackchain, South Korea
- Sooyeun Yang: Visual Analytics and Sensing, SUNY Korea, Master's program, South Korea

Research Mentor, Undergraduate Research Course, Purdue University

- Wookjin Chung: 6 credits of undergraduate research (Sp2018, Fal2019)
- Jonghyun Park: 6 credits of undergraduate research (Sp2018, Fa2019)
- Gun Wook Park: 6 credits of undergraduate research (Sp2017, Fa2017)
- Sharda Parth: 3 credits of undergraduate research (Sp2018)
- Yisong Yin: 6 credits of undergraduate research (Fa2016, Sp2017)

Curriculum Development and Educational Service

Graduate Course Development – MEC 559 Mobile Robotics and Autonomous Vehicles: Computer 2024 - present Vision and Control

 Students are to be trained to manipulate a Robot Operating System (ROS) package, work on related tasks

Graduate Course Development – MEC 510 Object-Oriented Programming for Scientists and 2022 – present Engineers: Visual Analytics and Sensing

 Providing Computer Vision (CV) and Machine Learning (ML) techniques in various mechanical engineering subjects

High School Credit System and Curriculum

2016 - 2017

 Chosen and served as an instructor for the 16-hour course "Computer Vision and Sustainable Cities Applications" organized by Incheon Metropolitan City Office of Education

TRAILS: Teachers and Researchers Advancing Integrated Lessons in STEM, *Purdue University*

2016 - 2017

• Supported by NSF under Grant No. NSF-1513248

• Participated as a graduate research assistant in promoting practices that increase students' motivations and capacities to pursue careers in STEM area.

SLED: Science Learning through Engineering Design, *Purdue University*

2015-2016

- Supported by NSF under Grant No. NSF-0962840
- Participated as a graduate research assistant in collaboration between STEM disciplinary faculty and grades 3-6 teachers.

SYNERGISTIC LEADERSHIP POSITION

Organizing Committee & Session Organizer & Session Chair for a Conference		
ICMR 2024, Busan, South Korea	12/2024	
AeroNDT 2023, Busan, South Korea	11/2023	
KSME Annual Meeting 2023, Incheon, South Korea	11/2023	
PHM Korea 2023, Seoul, South Korea	07/2023	
KSME-Reliability Division Annual Meeting 2023, Jeju, South Korea	03/2023	
KSME Annual Meeting 2022, Jeju, South Korea	11/2022	
PHM Korea 2022, Seoul, South Korea	07/2022	
 KSME-Reliability Division Annual Meeting 2022, Jeju, South Korea 	03/2022	
PHM Korea 2021, Jeju, South Korea	07/2021	
PHM Asia-Pacific 2021, Jeju South Korea	07/2021	
Banquet Master & MC service for a conference		
AeroNDT 2023, Busan, South Korea	11/2023	
PHM Korea 2023, Seoul, South Korea	07/2023	
Seminar Organizer		
Human-Machine Collaboration through MR & VR, SUNY Korea, Incheon, South Korea	10/2022	
 Hosted Prof. Chul Min Yeum, University of Waterloo, to hold an open seminar to SUNY 		
Korea community		
Lecture Series Co-Organizer	Twice every year	
Annual PHM Lecture Series for Industry, Yonsei University, Seoul, South Korea		
 Assisted organizing 3-days lecture series and was in charge of generating and online publishing high-quality video disseminating PHM workflow 		
Session Chair	07/2022	
Korean Society of Prognostics and Health Management (KSPHM) 2022, Seoul, South Korea		
 Served as a chair of the session "Future Mobility and Battery" 		
Colloquium Organizer	06/2022	
Two Departments Collaborating Seminar (Biomedical Engineering at Purdue Univ. and		
Mechanical Engineering at SUNY Korea), SUNY Korea, Incheon, South Korea		
 Hosted 6 prestigious scholars for this colloquium (3 from Purdue and 3 from SUNY Korea) 		
to share ideas with SUNY Korea students and searching future collaboration between two		
institutions		
Workshop Director	04/2019	

Workshop Director

04/2019

4th Midwest Smart Structure Colloquium at Purdue University, West Lafayette, IN, USA

 Organize, design, and direct a 3-days colloquium with 50 participants which is held in Bowen Laboratory at Purdue University

HONORS & AWARDS

<u>Awards</u>	
Outstanding Presentation Award from Intl. Conf. on Precision Engineering and Sustainable	07/2025
Manufacturing (PRESM 2025)	
 "Physics-informed Neural Network (PINN) and Hyper-realistic Digital Twin (3DGS) for 	
Predictive Engineering System Assessment" presented by Jongseong Choi*	
Young Scientist Award from Korean Society of Mechanical Engineers Reliability Division 2025	04/2025
The paper entitled "EV-PINN: Electric Vehicle Battery Surrogate Model using Transformer-	
Based Physics Informed Neural Network" and many other contributions in the society	
Grand Prize from "Idea Challenge Competition" held by Korean Society of Mechanical Engineers	12/2024
Chungcheong Division and KIMM 2024	
 "Physics-Informed Neural Network for EV Battery Prediction" authored by Hansol Lim, 	
Jeewon Lee, Hanbeom Chang, Sooyeun Yang, and Jongseong Choi*	
Outstanding Paper Award from 7th Intl. Conf. on Materials and Reliability (ICMR 2025)	12/2024
 "Development of a 3D Gaussian Splatting Digital Twining Platform for Remote Ship 	,
Assessment" authored by Jeewon Lee, Hansol Lim, <u>Jongseong Choi*</u> , Sangho Song, Jaechul	
Park, and Hwasup Jang.	
Best Poster Award from Annual Conf. of the PHM Korea Society (PHM Korea 2024)	10/2024
"LiDAR-Camera based Real-time 3D Reconstruction with Mixed Reality Visualization	,
System" authored by Hanbeom Chang and Jongsoeng Choi*	
Outstanding Thesis Award from Korean Society of Mechanical Engineers Reliability Division 2024	03/2024
 Mr. Ricardo Ortiz's Master's Thesis entitled "Autonomous Manipulation of Unmanned 	,
Ground Vehicle (UGV) with an User-Guided-Path on a Map: Quantitative Simulation and	
Analysis", supervised by <u>Jongseong Choi</u>	
Outstanding Paper Award from 14 th Intl. Symposium on NDT in Aerospace (AeroNDT 2023)	11/2023
 "Real-Time 3D Video Generation Using NeRF", authored by Hansol Lim and <u>Jongseong</u> 	,
<u>Choi*</u> . Only 4 papers were selected for this award among all papers submitted to the	
conference.	
Best Paper Award from 14 th Intl. Symposium on NDT in Aerospace (AeroNDT 2023)	
 "Region of Interest Locator with Digital Twin Model Generation of Large-Scale Facility", 	11/2023
authored by Jonathan Boyack, Hansol Lim, Alfredo Valenzuela, Jongseong Choi*, Sangho	,
Song, Yongseok Choi, and Dongguk Im. Only 10 papers were selected for this award among	
all papers submitted to the conference.	
Excellent Presentation Award from Korean Society of Mechanical Engineers Annual Meeting 2023	11/2023
The paper entitled "Seamless 3D Scene Control of NeRF Generated Digital Twin	,
Environments", authored by Hansol Lim and Jongseong Choi*, received the Excellent	
Presentation Award.	
Best Paper Award from Korean Society of Mechanical Engineers Annual Meeting 2023	11/2023
The paper entitled "Falling Hazard Assessment Application: Automated Labelling Large	,
Data Sets for Transfer Learning Models", authored by Jonathan Boyack and Jongseong	
Choi*, received the Best Paper Award.	
Outstanding Project Award from Incheon Technopark (ITP)	11/2023
The team MEIC (Ricardo Ortiz, Jonathan Boyakck, Alfredo Valenzuela, and Sambridha	11,2023
Bhattarai, supervised by Prof. Brad Choi, won "2023 Global Product-Service Localization	
Research Award Competition" held by ITP	

The Early-Career Scientist Award from Annual Conference of the PHM Korea Society (PHM Korea 2023)	07/2023	
 Dr. Jongseong Brad Choi talk is entitled "Engineering-Soft-Power engaged visualization analytics and human-machine collaboration remote assessment for large-scale structures" and won the Promising Young Scientist Award. 		
Best Paper Award from Annual Conference of the PHM Korea Society (PHM Korea 2023)	07/2023	
 The paper entitled "Real-Time, Non-Intrusive Inspection of Structures and Machines Using Visual Analytics and SfM-Based Digital Twin Generation", authored by Hansol Lim and <u>Jongseong Choi*</u>, received the Best Paper Award. 		
Best Paper Award from Korean Society of Mechanical Engineering Annual Meeting 2022	11/2022	
The paper entitled "A Real-Time Log Data Analytics-based Electric Vehicle Path	·	
Optimization", authored by Jonathan Boyack and Jongseong Choi* won the best paper		
award. Only 2 papers were selected for this award among all papers submitted to the		
Reliability Division in KSME.		
Best Paper Award from Korean Society of Mechanical Engineering Annual Meeting 2022, KSME	11/2022	
 The poster entitled "Indoor Navigation System Designed for a Safety of Construction Site", 		
authored by Pureun Jeong, Jimin Shin, Seung Hyun Cha, <u>Jongseong Choi*</u> won the best		
paper award. Only 2 papers were selected for this award among all papers submitted to		
the Reliability Division in KSME.		
Outstanding Project Award from Incheon Technopark (ITP)		
• The team MEIC (Jonathan Boyakck, Ricardo Ortiz, and Jee Won Lee, supervised by Prof.	11/2022	
Brad Choi, won "2022 Global Product-Service Localization Research Award Competition"		
held by ITP		
Travel Award & Workshop Invitation from NHERI RAPID Experimental Facility, NSF	07/2019	
• This award selects 20 attendees who has professional research background for the RAPID		
4 days Equipment Training Workshop at the University of Washington, Seattle, as well as		
support up to \$1,500 Travel Fund.		
Travel Award for Conference from College of Engineering, Purdue University	05/2018	
Honorable Mentions from 3 rd Midwest Smart Structure Colloquium, <i>University of Illinois (UIUC)</i>	10/2017	
• This award recognizes excellence PhD candidates supporting up to \$1,000 for 2019		
EWSHM conference at Hilton Hotel, Manchester, UK		
Resident Assistant Scholarship from University of Mississippi	08/2012 – 08/2013	
Honor Program Scholarship from University of Mississippi	01/2011	
• This scholarship is awarded to prominent undergraduate students in the School of		
Engineering.		
PROFESSIONAL TALKS & PRESENTATION		
[T23] Invited Speaker, "Hyper-Realistic Digital Twin and 3D Perception for Predictive	9/2025	
Engineering System Assessment", Dept. of Math Graduate Seminar Series in Ewha		
Womans University, Seoul, South Korea		
[T22] Invited Speaker, "Digital Twin-based Structural Anomaly Detection Technology Utilizing	8/2025	
Visual Intelligence", Workshop on Advanced SMR Design Technologies held by Korea		
Hydro & Nuclear Power (KHNP), Seoul, South Korea		
[T21] Invited Speaker, "Hyper-realistic 3D Neural Rendering Technology and Physics-Informed	7/2025	
Neural Networks for Intelligent Industrial Equipment Prognostics and Health		

	Management", Seminar Central Research Institute, Korea Hydro & Nuclear Power (KHNP),	
[T20]	Daejeon, South Korea Invited Lecturer, "Physics-Informed Neural Network; History and Current", Workshop on Industrial Application Technologies in the Energy and Machinery Sector for Carbon Neutrality, Incheon, South Korea	1/2025
[T19]	•	1/2025
[T18]	Invited Speaker , "Visual Analytics; History and Current", Autonomous Vehicle Research Society, Institute of Control, Robotics and Systems (ICROS), Holiday Inn Songdo, South Korea	10/2024
[T19]	Invited Speaker, "Human-Machine Distributed Collaborative Remote Sensing and Visual Analytics for Asset Assessment", ME Graduate School Seminar Series, UNIST, South Korea	10/2024
[T18]	Invited Plenary Speaker, "Visual Analytics; History and Current", Inha University 70th anniversary symposium (인하대 개교 70 주년 기념 국제 심포지엄), Inha University, South Korea	04/2024
[T17]	Invited Speaker , "Remote Sensing through Engineering-Soft-Power", Korea Electronics Technology Institute (KETI), South Korea	12/2023
[T16]	Invited Speaker, "A Real-Time Log Data Analytics-based Electric Vehicle Path Optimization", Argonne National Lab., IL, USA	05/2023
[T15]	Invited Guest Lecturer , "Human-Machine Collaborative Remote Monitoring and Sensing", Korean Register, Busan, South Korea	12/2022
[T14]	Invited Guest Lecturer , "Human-Machine Collaborative Remote Monitoring and Sensing", ME Seminar Series, Hanyang University, Seoul, South Korea	11/2022
[T13]	Invited Guest Lecturer , "Computer Vision engaged Infrastructure Remote Sensing", Dept. Architecture Engineering Seminar Series, Inha University, Incheon, South Korea	11/2022
[T12]	Invited Speaker, "Citizen Engaged Infrastructure Assessment and Remote Sensing", Young Promising Scientists Session (유망과학자 세션), Korean Society of Mechanical Engineers (KSME) Annual Conference 2022, Jeju, South Korea	11/2022
[T11]	Invited Guest Lecturer, "Cultural Heritage Long-term Preservation and Monitoring". National Museum of Modern and Contemporary Art, Cheongju, South Korea	09/2022
[T10]	Invited Guest Lecturer, "Citizen Engaged Infrastructure Assessment and Remote Monitoring", Artificial Intelligence Winter School, The Korean Society for Mechanical Engineers (KSME) – Al-Machine Research Group, KAIST, Daejeon, South Korea	02/2022
[T9]	Research Seminar , "Al to Enable Water Quality Control", Magpiesoft co., Daejeon, South Korea	02/2022
[T8]	Research Seminar , "Al for Possible Military Applications", HANCOM Intelligence co., Seongnam, South Korea	11/2022
[T7]	Research Seminar, "Citizen Engaged Building Cultural Heritage Management", Incheon	11/2021
[T6]	City Hall, Incheon, South Korea Invited Speaker, "Automating Visual Data Analytics to Aid Lifecycle Management of Infrastructure toward Sustainable Cities", Conference on Toward 'Ontact' Industries through PHM (PHM Korea 2021), Korea Society for Prognostics and Health Monitoring (KSPHM), Jeju, South Korea	09/2021
[T5]	Research Seminar, "Infrastructure Management with Automated Vision Systems", Incheon City Museum, Incheon, South Korea	10/2021

[T4]	Research Seminar, "Vision-based visual inspection for large-scale infrastructure", Korea	09/2020
	Institute of Construction Technology (KICT), Ilsan, South Korea	
[T3]	Research Seminar, Midwest Smart Structure Colloquium (MSSC), Midwest area US	10/16, 10/17, 4/19
[T2]	Research Seminar, 9th European Workshop on SHM, Manchester, UK, July	08/2018
[T1]	Poster Session, Herrick board meeting, West Lafayette, IN, USA	11/2015, 11/2016,
		11/2018
DATENTS		

PAIENIS

[A7]	Jongseong Choi*(2025.04), 3D Gaussian Splatting Digital Twin Platform. Korean Patent No.	04/2025
	10-2025-0046922	
[A6]	Jongseong Choi*(2025.04), Digital Twin Generation System for Vision-Based Structural	04/2025
	Health Monitoring. Korean Patent No. 10-2025-0046923	
[A5]	Jongseong Choi*(2025.04), Digital Twin Generation System for Vision-Based Structural	04/2025
	Health Monitoring. Korean Patent No. 10-2025-0046923	
[A4]	Jongseong Choi* (2025.02), Speed log data and physical knowledge neural network-based	02/2025
	electric vehicle dynamic coefficient estimation and energy consumption prediction	
	method. Korean Patent No. 10-2025-0017752	
[A3]	Jongseong Choi* (2025.02), Gaussian Splatting-based LiDAR-RGB Multi-Sensor and	02/2025
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- [C30] Jonathan Boyack, & <u>Jongseong Choi*</u>, "Data Localization on A Digital Twin Model to Enable Remote Assessment: Implementation on a full-scale Ship Engine", 20th World Conference on Non-Destructive Testing 2024 (WCNDT 2024), Incheon, South Korea, May 27 31, 2024.
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- [C16] Jeewon Lee, Hanbeom Chang, <u>Jongseong Choi*</u>, and Chul Min Yeum, "Automated Pan-Tilt-Zoom Camera Control Enabling Long-Range Visual Exploration for Extraterrestrial Missions", Korean Society of Mechanical Engineers (KSME)-Reliability Division 2023, Jeju, South Korea, Mar 22 24, 2023.
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- [C12] (Best Paper Award) Jonathan Boyack & <u>Jongseong Choi*</u>, "A Real-Time Log Data Analytics-based Electric Vehicle Path Optimization", Korean Society of Mechanical Engineers (KSME) Annual Meeting 2022, Jeju, South Korea, Nov 9 12, 2022.
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- [C10] <u>Jongseong Choi</u> & Shirley J. Dyke*, "ARIO: Automatic Reconnaissance Image Organizer to Learn from Earthquake", Annual Conference of Korean Society of Mechanical Engineers, Division of Reliability, Jeju, South Korea, Mar 23 25, 2022.
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- [C2] Chul Min Yeum*, <u>Jongseong Choi</u>, & Shirley J. Dyke (2017), "Automated Region-of-Interest Localization and Classification for Visual Assessment on Civil Infrastructure," Proceedings of the 11th International Workshop on Structural Health Monitoring, Stanford, CA, September 12-14, 2017.
- [C1] Chul Min Yeum*, <u>Jongseong Choi</u>, & Shirley J. Dyke (2017), "Image Localization for Computer-enhanced Visual Inspection of Civil Infrastructure," Proceedings of Engineering Mechanics Institute Conference, San Diago, CA, United States, June 4-7, 2017.

PROPOSAL DEVELOPMENT to U.S. GOVERNMENT (5 generated, 1 awarded).

[P5]	Active Citizen Engagement to Enable Lifecycle Management of Infrastructure Systems	07/2016
	• (Funded under Grant No. CMMI-1645047) Co-authored successful proposal with funded	
	\$100,000 from National Science Foundation (NSF).	
[P4]	Automating Damage Quantification, Localization and BIM Updating Using Optical Data	02/2020
	• Co-authored successful proposal and requested \$400,000 to National Science Foundation (NSF).	
[P3]	HDBE (E-Defense): Enabling Building Damage Assessment by Engaging Remote Experts	01/2018
	 Co-authored and requested \$700,000 to National Science Foundation (NSF). 	
[P3]	S&SA: Autonomous Infrastructure Inspection and Condition-Based Maintenance	05/2017
	 Co-authored proposal and requested to National Science Foundation (NSF). 	
[P1]	S&SA: Reconfigurable Aerial Robots for Intelligent Assessment to Industrial Disasters	11/2016
	Co-authored proposal and requested to National Science Foundation (NSF).	